

# Probabilistic Software product lines<sup>\*</sup>

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**Abstract.** We introduce a probabilistic extension of our previous work **SPLA**: a formal framework to specify and analyze software product lines. We will use probabilistic information to identify those features that are more frequently used by computing the probability of having a feature in a specific software product line. We redefine the syntax of **SPLA** to include probabilistic operators and define new operational and denotational semantics. We prove that the expected equivalence between these two semantic frameworks holds. Our probabilistic framework is supported by a tool. We briefly comment on the characteristics of the tool and discuss the advantages of using probabilities to quantify the likelihood of having features in potential software product lines.

**Keywords;** Software Product Lines; Probabilistic Models; Formal Methods; Feature Models

## 1 Introduction

During the last years, software product lines (in short, **SPLs**) have become a widely adopted mechanism for efficient software development. The Carnegie Mellon Software Engineering Institute defines an **SPL** as “a set of software-intensive systems that share a common, managed set of features satisfying the specific needs of a particular market segment or mission and that are developed from a common set of core assets in a prescribed way” [31]. Basically, the main goal of **SPLs** is to increase the productivity for creating software products, which is achieved by selecting those software systems that are better for a specific criterion (e.g. a software system is less expensive than others, it requires less time to be processed, etc). Currently, different approaches for representing the product line organization can be found in the literature, such as **FODA** [26], **RSEB** [21] and **PLUSS** [27,19].

Graphical approaches are commonly used to model **SPLs**. Feature Oriented Domain Analysis [26] (in short, **FODA**) is a well-known graphical approach for

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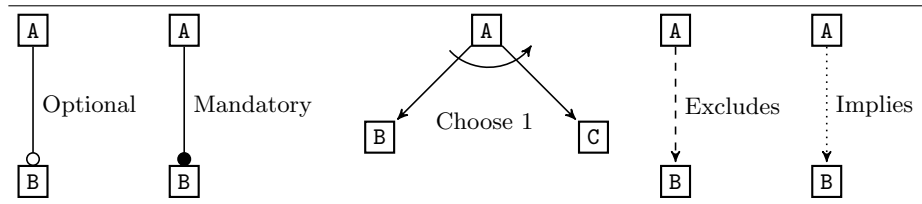


Fig. 1. FODA Diagram representation.

representing commonality and variability of systems. Figure 1 shows all FODA relationships and constraints. Although this kind of solutions is useful to easily model SPLs, a formal approach is needed for automatizing the analysis process and detecting errors in the early stages of the production process. It is therefore required that graphical representations are translated into mathematical entities [32]. In this case, the original graphical representation of FODA must be provided with a formal semantics [7]. This issue is solved by using SPLA [1], a formal framework to represent FODA diagrams using process algebras. SPLA can be applied not only to FODA, but also to represent other feature-related problems and variability models. Additionally, some of the existing formal approaches use algebras and semantics [37,24,25,1], while others use either propositional or first order logic [30,12,4,3,33].

It is worth to mention that the order in which features are processed to create a specific product is directly reflected in its final cost. In a previous work we introduced costs in our formal framework for representing the required effort to include a feature to the product under construction [8]. This cost may represent different aspects of a feature, such as lines of code of a given software component or effort, in human hours, to include a software component into a project, just to name a few, that usually depend on the target of the product line organization. Thus, efficiently processing features for building high quality products becomes a time-consuming and challenging task. Unfortunately, there are some situations where the representation of the SPL generates a combinatorial explosion, making unpractical to analyze all possible combinations. In order to alleviate this issue, in this paper we propose a probabilistic extension of our previous work SPLA. We use probabilistic information to identify those features that are more frequently used by computing the probability of having a feature in a specific SPL. Hence, the computation focuses on those features with a high probability to be present in the final product, reducing the total computation required for generating valid products. The proposed probabilistic extension has been fully implemented in a tool. In order to show its usefulness, we have conducted an experimental study where different models consisting of 1500 features have been analyzed. The obtained results are promising. In this case, 450 features have a probability equal to 0.75 to be included in a final product. This means that, at least, the 75% of the generated products are tested by only analyzing the 28% of the software components in the SPL.

The study of probabilistic extensions of formal methods can be dated back to the end of the 1980s. This is already a well established area, with many extensive contributions to include probabilistic information in classical formalisms (I/O Automata, Finite State Machines, (co-)algebraic approaches, among others) [28,20,10,34,29,9,17,15,22,2,36,23,16,13]. Although the addition of probabilistic information to model SPLs is relatively new, there are already several proposals in the literature [11,6,5,18]. In particular, very recent work [18] shows that statistic analysis allows users to determine relevant characteristics, like the certainty of finding valid products among complex models. Another approach [11] focuses on testing properties of SPLs, like reliability, by defining three verification techniques: a probabilistic model checker on each product, on a model range, and testing the behavior relations with other models. Some of these approaches describe models to run statistical analysis over SPLs, where pre-defined syntactic elements are computed by applying a specific set of operational rules [6,5]. These models demonstrate their ability to be integrated into standard tools like QFLan, Microsoft's SMT Z3 and MultiVeStA.

The rest of the paper is structured as follows. Section 2 presents our language. Section 3 is used to prove the equivalence between the operational and denotational semantics. In section 4 we extend our language to define how sets of features can be hidden. Section 5 shows our implementation of the denotational semantics for the probabilistic extension. Finally, section 6 presents our conclusions and some lines of future work.

## 2 SPLA<sup>P</sup>: syntax and semantics

In this section we introduce our language. In addition to present its syntax, we define an operational semantics and a denotational semantics. In the next section we will show the equivalence between these two semantic frameworks.

### 2.1 Syntax and operational semantics

Following our previous work [1,8], we will consider a set of features. We denote this set by  $\mathcal{F}$  and consider that  $A, B, C$  range over  $\mathcal{F}$ . We have a special feature  $\checkmark \notin \mathcal{F}$  to mark the end of a product. We consider a syntax similar to SPLA, where probabilities are introduced in the choice operator  $P \vee_p Q$  and in the optional feature operator  $\bar{A};_p P$ . We do not allow *degenerated* probabilities, that is, for all probability  $p$  we have  $0 < p < 1$ .

**Definition 1.** A *probabilitistic SPL* is a term generated by the following BNF expression:

$$P ::= \checkmark \mid \text{nil} \mid A; P \mid \bar{A};_p P \mid P \vee_p P \mid P \wedge P \mid \\ A \not\Rightarrow B \text{ in } P \mid A \Rightarrow B \text{ in } P \mid P \setminus A \mid P \Rightarrow A$$

where  $A, B \in \mathcal{F}$  and  $p \in (0, 1)$ . The set of terms of the algebra will be denoted by SPLA<sup>P</sup>.  $\square$

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<p><b>[tick]</b> <math>\frac{\checkmark \xrightarrow{1} \text{nil}}{\checkmark \xrightarrow{1} \text{nil}}</math></p> <p><b>[ofeat1]</b> <math>\frac{\bar{A};_p P \xrightarrow{A} P}{P \xrightarrow{A} P_1}</math></p> <p><b>[cho1]</b> <math>\frac{P \xrightarrow{A} P_1}{P \vee_q Q \xrightarrow{A} P_1}</math></p> <p><b>[con1]</b> <math>\frac{P \xrightarrow{A} P_1}{P \wedge Q \xrightarrow{A} P_1 \wedge Q}</math></p> <p><b>[con3]</b> <math>\frac{P \xrightarrow{q} \text{nil}, Q \xrightarrow{p} \text{nil}}{P \wedge Q \xrightarrow{p \cdot q} \text{nil}}</math></p> <p><b>[con4]</b> <math>\frac{P \xrightarrow{A} P_1, Q \xrightarrow{q} \text{nil}}{P \wedge Q \xrightarrow{p \cdot q} P_1}</math></p> <p><b>[req1]</b> <math>\frac{P \xrightarrow{C} P_1, C \neq A}{A \Rightarrow B \text{ in } P \xrightarrow{C} P_1 \Rightarrow B \text{ in } P_1}</math></p> <p><b>[req3]</b> <math>\frac{P \xrightarrow{p} \text{nil}}{A \Rightarrow B \text{ in } P \xrightarrow{p} \text{nil}}</math></p> <p><b>[excl1]</b> <math>\frac{P \xrightarrow{C} P_1, C \neq A, C \neq B}{A \not\Rightarrow B \text{ in } P \xrightarrow{C} P_1 \not\Rightarrow B \text{ in } P_1}</math></p> <p><b>[excl3]</b> <math>\frac{P \xrightarrow{B} P_1}{A \not\Rightarrow B \text{ in } P \xrightarrow{B} P_1 \setminus A}</math></p> <p><b>[forb1]</b> <math>\frac{P \xrightarrow{B} P_1, B \neq A}{P \setminus A \xrightarrow{B} P_1 \setminus A}</math></p> <p><b>[mand1]</b> <math>\frac{P \xrightarrow{p} \text{nil}}{P \Rightarrow A \xrightarrow{p} \checkmark}</math></p> <p><b>[mand3]</b> <math>\frac{P \xrightarrow{B} P_1, A \neq B}{P \Rightarrow A \xrightarrow{B} P_1 \Rightarrow A}</math></p>	<p><b>[feat]</b> <math>A; P \xrightarrow{A} P</math></p> <p><b>[ofeat2]</b> <math>\frac{\bar{A};_p P \xrightarrow{(1-p)} \text{nil}}{Q \xrightarrow{A} Q_1}</math></p> <p><b>[cho2]</b> <math>\frac{Q \xrightarrow{A} Q_1}{P \vee_p Q \xrightarrow{(1-p) \cdot q} Q_1}</math></p> <p><b>[con2]</b> <math>\frac{Q \xrightarrow{A} Q_1}{P \wedge Q \xrightarrow{\frac{A}{2}} P \wedge Q_1}</math></p> <p><b>[con5]</b> <math>\frac{P \xrightarrow{p} \text{nil}, Q \xrightarrow{A} Q_1}{P \wedge Q \xrightarrow{\frac{p \cdot q}{2}} Q_1}</math></p> <p><b>[req2]</b> <math>\frac{P \xrightarrow{A} P_1}{A \Rightarrow B \text{ in } P \xrightarrow{A} P_1 \Rightarrow B}</math></p> <p><b>[excl2]</b> <math>\frac{P \xrightarrow{A} P_1}{A \not\Rightarrow B \text{ in } P \xrightarrow{A} P_1 \setminus B}</math></p> <p><b>[excl4]</b> <math>\frac{P \xrightarrow{p} \text{nil}}{A \not\Rightarrow B \text{ in } P \xrightarrow{p} \text{nil}}</math></p> <p><b>[forb2]</b> <math>\frac{P \xrightarrow{p} \text{nil}}{P \setminus A \xrightarrow{p} \text{nil}}</math></p> <p><b>[mand2]</b> <math>\frac{P \xrightarrow{A} P_1}{P \Rightarrow A \xrightarrow{A} P_1}</math></p>
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$A, B, C \in \mathcal{F}, a \in \mathcal{F} \cup \{\checkmark\}$

**Fig. 2.**  $\text{SPLA}^{\mathcal{P}}$  operational semantics.

In Figure 2 we present the set of rules formally defining the operational behavior of  $\text{SPLA}^{\mathcal{P}}$ . These rules essentially coincide with the ones corresponding to  $\text{SPLA}$  [1], but with the addition of probabilities. Next we focus on the explanation of the role of probabilities. Rules **[tick]** and **[feat]** show the corresponding feature with probability 1. Rules **[ofeat1]** and **[ofeat2]** deal with the probabilistic optional feature. The feature can be chosen with probability  $p$  and can be rejected with probability  $1 - p$ . Let us note that both probabilities are not null. Rules **[cho1]** and **[cho2]** define the behavior of the probabilistic choice operator. The left branch is selected with probability  $p$  and the right one with probability  $1 - p$ . It is important to note that the rules for the conjunction operator, **[con1]**, **[con2]**, **[con4]** and **[con5]**, equitably distribute the probability between both branches, that is,  $\frac{1}{2}$ . We have preferred to use a simple definition of this operator, but it is easy to replace it by a more involved version of a probabilistic parallel operator [14]. Rule **[con3]** requires that both branches agree on the termination of a product.

We use *multisets* of transitions to consider different occurrences of the same transition. So, if a transition can be derived in several ways, then each derivation generates a different instance of this transition. For example, let us consider the term  $P = \mathbf{A}; \checkmark \vee_{\frac{1}{2}} \mathbf{A}; \checkmark$ . If we were not careful, then we would have the transition  $P \xrightarrow{\mathbf{A}}_{\frac{1}{2}} \checkmark$  only once, while we should have this transition twice. So, if a transition can be derived in several ways, then we consider that each derivation generates a different instance. In particular, we will later consider multisets of computations as well. We will use the delimiters  $\wr$  and  $\beth$  to denote multisets and  $\uplus$  to denote the union of multisets.

The following result, which proof is immediate, shows that successful termination leads to  $\mathbf{nil}$ .

**Lemma 1.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$  and  $p \in (0, 1]$ . We have  $P \xrightarrow{\checkmark}_p Q$  if and only if  $Q = \mathbf{nil}$ .  $\square$

Next we present some notions associated with the composition of consecutive transitions.

**Definition 2.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$ . We write  $P \xrightarrow{s}_p Q$  if there exist a sequence of consecutive transitions

$$P = P_0 \xrightarrow{a_1}_{p_1} P_1 \xrightarrow{a_2}_{p_2} P_2 \cdots P_{n-1} \xrightarrow{a_n}_{p_n} P_n = Q$$

where  $n \geq 0$ ,  $s = a_1 a_2 \cdots a_n$  and  $p = p_1 \cdot p_2 \cdots p_n$ . We say that  $s$  is a trace of  $P$ .

Let  $s \in \mathcal{F}^*$  be a trace of  $P$ . We define the product  $[s] \subseteq \mathcal{F}$  as the set consisting on all features belonging to  $s$ .

Let  $P \in \text{SPLA}^{\mathcal{P}}$ . We define the set of probabilistic products of  $P$ , denoted by  $\text{prod}^{\mathcal{P}}(P)$ , as the set

$$\{(pr, p) \mid p > 0 \wedge p = \sum \wr q \mid P \xrightarrow{s\checkmark}_q Q \wedge [s] = pr\}$$

We define the total probability of  $P$ , denoted by  $\text{TotProb}(P)$ , as the value  $\sum \wr p \mid \exists pr : (pr, p) \in \text{prod}^{\mathcal{P}}(P)\}$ . In addition, we define  $\text{waste}(P) = 1 - \text{TotProb}(P)$ .  $\square$

The following result shows some properties, concerning probabilities, of the operational semantics. In particular, we have that the probability of (sequences of) transitions is greater than zero and that the probabilities of products belong to  $[0, 1]$ .

**Lemma 2.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$ . We have the following results.

1. If  $P \xrightarrow{\mathbf{A}}_p Q$  then  $p \in (0, 1]$ . If  $P \xrightarrow{s}_p Q$  then  $p \in (0, 1]$ .
2.  $\sum \wr p \mid \exists \mathbf{A} \in \mathcal{F}, Q \in \text{SPLA}^{\mathcal{P}} : P \xrightarrow{\mathbf{A}}_p Q\} \in [0, 1]$ .
3.  $\sum \wr p \mid \exists s \in \mathcal{F}^*, Q \in \text{SPLA}^{\mathcal{P}} : P \xrightarrow{s\checkmark}_p Q\} \in [0, 1]$ .
4.  $\text{TotProb}(P) \in [0, 1]$ .

$\square$

Next we prove an important property of our language: its consistency. We say that a non-probabilistic SPL model is *consistent* if it has products [1]. In our case, we can define consistency by having  $\text{TotProb}(P) > 0$ . We will prove that a translation from our probabilistic framework into the non-probabilistic one keeps consistency in the expected way.

**Definition 3.** We define the translation function  $\text{np} : \text{SPLA}^{\mathcal{P}} \mapsto \text{SPLA}$  as follows:

$$\text{np}(P) = \begin{cases} \checkmark & \text{if } P = \checkmark \\ \text{nil} & \text{if } P = \text{nil} \\ A; \text{np}(P) & \text{if } P = A; P \\ \bar{A}; \text{np}(P) & \text{if } P = \bar{A};_p P \\ \text{np}(P) \vee \text{np}(Q) & \text{if } P \vee_p Q \\ \text{np}(P) \wedge \text{np}(Q) & \text{if } P \wedge Q \\ A \Rightarrow B \text{ in } \text{np}(P) & \text{if } A \Rightarrow B \text{ in } P \\ A \not\Rightarrow B \text{ in } \text{np}(P) & \text{if } A \not\Rightarrow B \text{ in } P \\ \text{np}(P) \Rightarrow A & \text{if } P \Rightarrow A \\ \text{np}(P) \setminus A & \text{if } P \setminus A \end{cases}$$

□

The proof of the following result is straightforward by taking into account that our operational semantics rules are the same, if we discard probabilities, as in [1]. Therefore, any sequence of transitions derived in the probabilistic model can be also derived in the non probabilistic one. In addition, by Lemma 2 we know that any derived trace in the probabilistic model has a non null probability.

**Theorem 1.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$ . We have  $P \xrightarrow{s} \text{np}(P)$  if and only if  $P \xrightarrow{s} \text{np}(Q)$ . Moreover, we have  $pr \in \text{prod}(\text{np}(P))$  if and only if there exists  $p > 0$  such that  $(pr, p) \in \text{prod}^{\mathcal{P}}(P)$ . □

## 2.2 Denotational Semantics

Next we define a denotational semantics for the terms of our language. The main features of the semantic domain are that we consider products (set of features) with probability such that the sum of all the probabilities associated with products belongs to the interval  $(0, 1]$ . First, we precisely define the members of the semantic domain.

**Definition 4.** We define the semantic domain  $\mathcal{M}$  as the largest set  $\mathcal{M} \subseteq \mathcal{P}(\mathcal{P}(\mathcal{F}) \times (0, 1])$  such that if  $A \in \mathcal{M}$  then the following conditions hold:

- If  $(P, q) \in A$  and  $(P, r) \in A$  then  $q = r$ .
- $0 \leq \sum \{q \mid \exists P : (P, q) \in A\} \leq 1$ .

Let  $M$  be a multiset with elements in the set  $\mathcal{P}(\mathcal{F}) \times [0, 1]$ . We define the operator **accum** as follows:

$$\mathbf{accum}(M) = \left\{ (P, p) \mid p = \sum_{(P, q) \in M} q \wedge p > 0 \right\}$$

□

Even though the elements of the semantic domain are sets of pairs (product, probability), with at most one occurrence of a given product, we will use multisets as auxiliary elements in our semantic functions. Then, the function  $\mathbf{accum}(M)$  will *flatten* them to become sets. The following result is immediate.

**Proposition 1.** Let  $M$  be a multiset with elements in the set  $\mathcal{P}(\mathcal{F}) \times [0, 1]$ . If  $1 \geq \sum \lambda q \mid (P, q) \in M \rfloor$  then  $\mathbf{accum}(M) \in \mathcal{M}$ . □

Next we define the operators of the denotational semantics. As we have said before, multisets meeting the conditions of the previous result appear when defining these operators. For instance, the prefix operator  $\llbracket \mathbf{A}; \cdot \rrbracket(M)$  should add feature  $\mathbf{A}$  to any product in  $M$ . Let us suppose that  $M = \{(\{\mathbf{B}, \mathbf{A}\}, \frac{1}{2}), (\{\mathbf{B}\}, \frac{1}{2})\}$ . If we add  $\mathbf{A}$  to the products of  $M$  then we obtain the product  $\{\mathbf{A}, \mathbf{B}\}$  twice, having probability  $\frac{1}{2}$  associated with each occurrence. So we need to apply the function **accum** to accumulate both probabilities and obtain a single product with probability 1.

**Definition 5.** Let  $M, M_1, M_2 \in \mathcal{M}$ ,  $\mathbf{A}, \mathbf{B} \in \mathcal{F}$  and  $p \in (0, 1]$ . For any operator appearing in Definition 2.1 we define its denotational operator as follows:

- $\llbracket \mathbf{nil} \rrbracket^{\mathcal{P}} = \emptyset$
- $\llbracket \checkmark \rrbracket^{\mathcal{P}} = \{(\emptyset, 1)\}$
- $\llbracket \mathbf{A}; \cdot \rrbracket^{\mathcal{P}}(M) = \mathbf{accum}(\lambda(\{\mathbf{A}\} \cup P, p) \mid (P, p) \in M \rfloor)$
- $\llbracket \bar{\mathbf{A}}; r \cdot \rrbracket^{\mathcal{P}}(M) = \mathbf{accum}(\lambda(\emptyset, 1 - r) \rfloor \uplus \lambda(\{\mathbf{A}\} \cup P, r \cdot p) \mid (P, p) \in M \rfloor)$
- $\llbracket \cdot \vee_r \cdot \rrbracket^{\mathcal{P}}(M_1, M_2) = \mathbf{accum} \left( \lambda(P, r \cdot p) \mid (P, p) \in M_1 \rfloor \uplus \lambda(Q, (1 - r) \cdot q) \mid (Q, q) \in M_2 \rfloor \right)$
- $\llbracket \cdot \wedge \cdot \rrbracket^{\mathcal{P}}(M_1, M_2) = \mathbf{accum} \left( \lambda(P \cup Q, p \cdot q) \mid (P, p) \in M_1, (Q, q) \in M_2 \rfloor \right)$
- $\llbracket \mathbf{A} \Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(M) = \mathbf{accum} \left( \lambda(P, p) \mid (P, p) \in M, \mathbf{A} \notin P \rfloor \uplus \lambda(\{\mathbf{B}\} \cup P, p) \mid (P, p) \in M, \mathbf{A} \in P \rfloor \right)$
- $\llbracket \mathbf{A} \not\Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(M) = \{(P, p) \mid (P, p) \in M, \mathbf{A} \notin P\} \cup \{(P, p) \mid (P, p) \in M, \mathbf{B} \notin P\}$
- $\llbracket \cdot \Rightarrow \mathbf{A} \rrbracket^{\mathcal{P}}(M) = \llbracket \mathbf{A}; \cdot \rrbracket^{\mathcal{P}}(M)$
- $\llbracket \cdot \setminus \mathbf{A} \rrbracket^{\mathcal{P}}(M) = \{(P, p) \mid (P, p) \in M, \mathbf{A} \notin P\}$

□

It is easy to check that all the multisets appearing in the previous definition meet the conditions of Proposition 1. So, the operators are actually well defined. This is formalized in the following result.

**Proposition 2.** Let  $M, M_1, M_2 \in \mathcal{M}$ ,  $p \in (0, 1]$  be a probability, and  $\mathbf{A}, \mathbf{B} \in \mathcal{F}$  be features. We have:

- $\llbracket \mathbf{A}; \cdot \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$
- $\llbracket \overline{\mathbf{A}}; r \cdot \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$
- $\llbracket \cdot \vee_r \cdot \rrbracket^{\mathcal{P}}(M_1, M_2) \in \mathcal{M}$
- $\llbracket \cdot \wedge \cdot \rrbracket^{\mathcal{P}}(M_1, M_2) \in \mathcal{M}$
- $\llbracket \mathbf{A} \Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$
- $\llbracket \mathbf{A} \not\Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$
- $\llbracket \cdot \Rightarrow \mathbf{A} \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$
- $\llbracket \cdot \setminus \mathbf{A} \rrbracket^{\mathcal{P}}(M) \in \mathcal{M}$

□

### 3 Equivalence between the operational and denotational semantics

We have defined two different semantics for our language: the products derived from the operational semantics and the products obtained from the denotational semantics. It is important that both semantics coincide, so that we can chose the approach that suits better in any moment. The proof of the following result is an immediate consequence of Lemmas 3–11 (see Appendix A of the paper).

**Proposition 3.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$  be terms,  $\mathbf{A}, \mathbf{B} \in \mathcal{F}$  be features and  $q \in (0, 1)$ , be a probability. We have the following results:

$$\begin{aligned}
\text{prod}^{\mathcal{P}}(\mathbf{A}; P) &= \llbracket \mathbf{A}; \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P)) \\
\text{prod}^{\mathcal{P}}(\overline{\mathbf{A}};_q P) &= \llbracket \overline{\mathbf{A}};_q \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P)) \\
\text{prod}^{\mathcal{P}}(P \vee_q Q) &= \llbracket \cdot \vee_q \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P), \text{prod}^{\mathcal{P}}(Q)) \\
\text{prod}^{\mathcal{P}}(P \wedge Q) &= \llbracket \cdot \wedge \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P), \text{prod}^{\mathcal{P}}(Q)) \\
\text{prod}^{\mathcal{P}}(P \Rightarrow \mathbf{A}) &= \llbracket \cdot \Rightarrow \mathbf{A} \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P)) \\
\text{prod}^{\mathcal{P}}(P \setminus \mathbf{A}) &= \llbracket \cdot \setminus \mathbf{A} \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P)) \\
\text{prod}^{\mathcal{P}}(\mathbf{A} \Rightarrow \mathbf{B} \text{ in } P) &= \llbracket \mathbf{A} \Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P)) \\
\text{prod}^{\mathcal{P}}(\mathbf{A} \not\Rightarrow \mathbf{B} \text{ in } P) &= \llbracket \mathbf{A} \not\Rightarrow \mathbf{B} \text{ in } \cdot \rrbracket^{\mathcal{P}}(\text{prod}^{\mathcal{P}}(P))
\end{aligned}$$

□

Finally, we have the previously announced result. The proof, by structural induction on  $P$ , is easy from Proposition 3.

**Theorem 2.** Let  $P \in \text{SPLA}^{\mathcal{P}}$  be a term,  $pr \subseteq \mathcal{F}$  be a product, and  $p \in (0, 1]$  be a probability. We have that  $(pr, p) \in \llbracket P \rrbracket^{\mathcal{P}}$  if and only if  $(pr, p) \in \text{prod}^{\mathcal{P}}(P)$ .

□

### 4 Hiding sets of features

The probability of a single feature in a software product line is a measure of the occurrences of this feature in the set of products. For instance, in case of testing, it is interesting to know the most frequent components to focus our analysis on these components. In order to compute the probability of a set of features we are going to *hide* other features. We hide features because it is usually not feasible to compute all the products of the software product line. However, we expect to achieve our goal if we restrict ourselves to a subset of features. So, non



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$$\begin{array}{cc}
\text{[hid1]} \frac{P \xrightarrow{\mathbf{A}}_p P', \mathbf{A} \in \mathcal{A}}{P[\mathcal{A}] \xrightarrow{\perp}_p P'[\mathcal{A}]} & 
\text{[hid2]} \frac{P \xrightarrow{\mathbf{A}}_p P', \mathbf{A} \notin \mathcal{A}}{P[\mathcal{A}] \xrightarrow{\mathbf{A}}_p P'[\mathcal{A}]}
\end{array}$$


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**Fig. 3.** Operational semantics for the hiding operator

interesting features are transformed into a new feature, denoted by  $\perp \notin \mathcal{F}$ , and we consider the set  $\mathcal{F}_\perp = \mathcal{F} \cup \{\perp\}$ .

We extend the set of operators with a new one: hiding a set of features in a term.

**Definition 6.** Let  $\mathcal{A} \subseteq \mathcal{F}$  be a subset of features and  $P \in \text{SPLA}^{\mathcal{P}}$  be a term. We have that  $P[\mathcal{A}]$  denotes the hiding of the features in  $\mathcal{A}$  for the term  $P$ .  $\square$

We need to define the semantics of the new operator. The operational semantics is given by the rules appearing in Figure 3. In order to define the denotational semantics of the new operator, first we need an auxiliary function that hides some features of a given product.

**Definition 7.** Let  $pr \subseteq \mathcal{F}$  be a product and  $\mathcal{A} \subseteq \mathcal{F}$  be a set of features. The *hiding of the set  $\mathcal{A}$  in  $pr$* , denoted by  $pr[\mathcal{A}]$ , is defined as follows:

$$pr[\mathcal{A}] = \{\mathbf{A} \mid \mathbf{A} \in pr \wedge \mathbf{A} \notin \mathcal{A}\} \cup \begin{cases} \{\perp\} & \text{if } pr \cap \mathcal{A} \neq \emptyset \\ \emptyset & \text{if } pr \cap \mathcal{A} = \emptyset \end{cases}$$

Analogously, for any sequence  $s \in \mathcal{F}^*$  we consider that  $s[\mathcal{A}]$  denotes the trace produced from  $s$  after replacing all the occurrences of features belonging to  $\mathcal{A}$  by the symbol  $\perp$  in  $s$ .  $\square$

**Definition 8.** Let  $M \in \mathcal{M}$  and  $\mathcal{A} \subseteq \mathcal{F}$ . We define:

$$\llbracket \cdot[\mathcal{A}] \rrbracket^{\mathcal{P}} = \text{accum}(\lambda (pr[\mathcal{A}], p) \mid (pr, p) \in M)$$

$\square$

Finally, we have to prove that the operational semantics and the denotational semantics coincide. The proof of the following result is an immediate consequence of Proposition 6 (see Appendix B).

**Proposition 4.** Let  $\mathcal{A} \subseteq \mathcal{F}$  be a subset of features and  $P \in \text{SPLA}^{\mathcal{P}}$  be a term. We have  $\text{prod}^{\mathcal{P}}(P[\mathcal{A}]) = \llbracket \text{prod}^{\mathcal{P}}(P)[\mathcal{A}] \rrbracket^{\mathcal{P}}$ .  $\square$

As usual in process algebras, it would be desirable that the hiding operator is *derived*, that is, given a syntactic term, there exists a semantically equivalent term without occurrences of the hiding operator. The next proposition shows that it is possible to *remove* the hiding operator from any term. The idea is to

substitute any occurrence of the hidden actions by the symbol  $\perp$ . However, it is necessary to take into account that we cannot hide actions that appear in the restriction operators and, therefore, these cases are not contemplated. The proof of the following result is easy by structural induction and by Proposition 4.

**Proposition 5.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$  be terms,  $r \in (0, 1]$  be a probability, and  $\mathcal{A} \subseteq \mathcal{F}$  be a set of hidden actions. We have the following results:

$$\begin{aligned} \llbracket \checkmark[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket \checkmark \rrbracket^{\mathcal{P}} \\ \llbracket \text{nil}[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket \text{nil} \rrbracket^{\mathcal{P}} \\ \llbracket (\mathbf{A}; P)[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \begin{cases} \llbracket \perp; (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} & \text{if } A \in \mathcal{A} \\ \llbracket \mathbf{A}; (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} & \text{if } A \notin \mathcal{A} \end{cases} \\ \llbracket (\overline{\mathbf{A}};_r P)[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \begin{cases} \llbracket \overline{\perp};_r (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} & \text{if } A \in \mathcal{A} \\ \llbracket \overline{\mathbf{A}};_r (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} & \text{if } A \notin \mathcal{A} \end{cases} \\ \llbracket (P \vee_P Q)[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket (P[\mathcal{A}]) \vee_P (Q[\mathcal{A}]) \rrbracket^{\mathcal{P}} \\ \llbracket (P \wedge Q)[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket (P[\mathcal{A}]) \wedge (Q[\mathcal{A}]) \rrbracket^{\mathcal{P}} \\ \text{If } \mathbf{A}, \mathbf{B} \notin \mathcal{A} \text{ then } \llbracket (\mathbf{A} \Rightarrow \mathbf{B} \text{ in } P)[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket \mathbf{A} \Rightarrow \mathbf{B} \text{ in } (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} \\ \text{If } \mathbf{A}, \mathbf{B} \notin \mathcal{A} \text{ then } \llbracket (\mathbf{B} \not\Rightarrow \mathbf{P} \text{ in } )[\mathcal{A}] \rrbracket^{\mathcal{P}} &= \llbracket \mathbf{A} \not\Rightarrow \mathbf{B} \text{ in } (P[\mathcal{A}]) \rrbracket^{\mathcal{P}} \end{aligned}$$

□

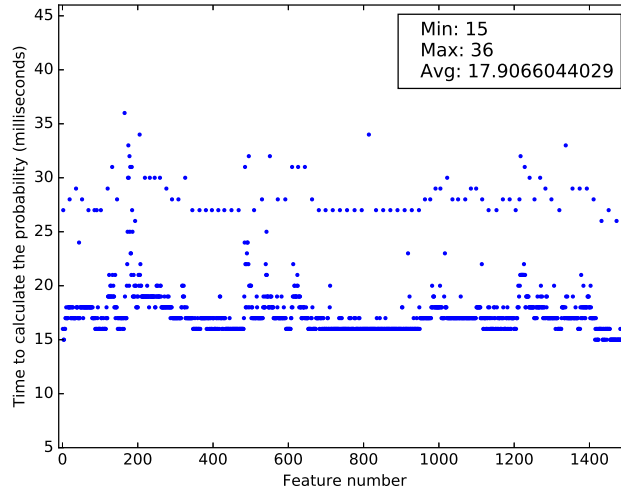
## 5 Implementation

This section presents the results obtained from an experimental study to show the applicability of our approach. In order to carry out this study, we have developed a tool to implement the proposed probabilistic extension. The source code of this tool is available at the main project site.<sup>1</sup> We have used a variability model consisting of 1500 features. This variability model was randomly generated using BeTTy [35]. The parameters for generating the BeTTy model are the following:

- The probability of having a mandatory feature is 0.2.
- The probability of having an optional feature is 0.3.
- The probability of having a feature in a *choose-1* relation is 0.25.
- The probability of having a feature in a *parallel* relation is 0.25.

In the field of SPLs analysis, the use of probabilistic methods carries two practical applications. The first one consists in calculating the probability of having a feature in a specific product. This allows us to efficiently assign resources by prioritizing those features with a high probability of being included into the SPL. The second application consists in estimating the testing coverage in the product line. This allows us to calculate those products that can be generated in the testing process.

<sup>1</sup> [http://ccamacho.github.io/phd/resources/03\\_splap.tar](http://ccamacho.github.io/phd/resources/03_splap.tar)



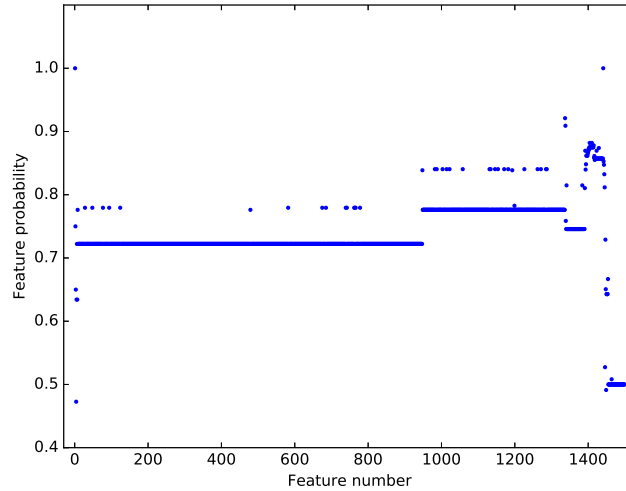
**Fig. 4.** Computing time analysis for a model consisting of 1500 features.

Figure 4 shows the computing time required to calculate the probability of having each feature in a product. It is important to remark that there is a small variation in the processing time for calculating the probability of each single feature. We think that this variation is mainly caused by the inherent noise of the node where the experiment is launched (e.g. disk latencies, operating system overhead, memory paging, etc.) and, therefore, it is not related to the algorithm itself.

Since the processing time for each feature is relatively low, being around milliseconds, a single delay in the process scheduling may have a direct impact in the overall algorithm performance. Hence, this overhead can be considered insignificant since, in general, the time for processing each feature in the model ranges from 15 to 28 milliseconds.

The model used in the experiments has been executed several times, providing similar results. That is, the major part of the features require between 15 and 20 milliseconds to be processed, while there is a small portion of them requiring a processing time between 20 and 38 milliseconds.

Figure 5 shows the probability of each feature in the analyzed model, where the  $x$ -axis represents the feature ID and the  $y$ -axis represents the probability. For the sake of clarity, we provide a chart by sorting the features using its probability as sorting criteria (see Figure 6). This chart clearly shows that there exist different groups of features having a similar probability. In this case, there are 450 features with, at least, a probability equal to 0.75 of being in a final product. As a conclusion, this analysis might allow us to establish that by testing




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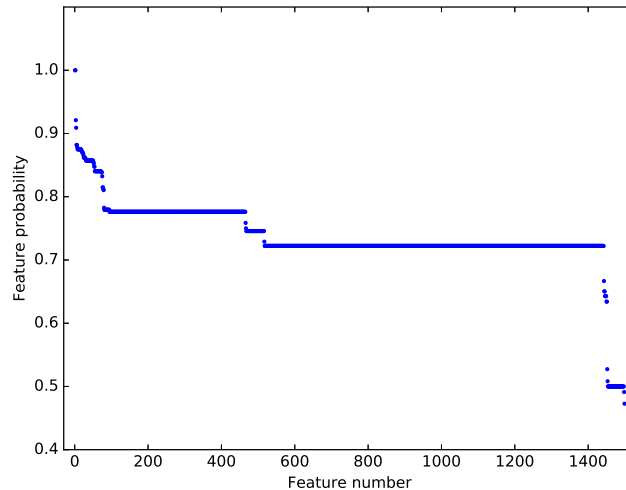
**Fig. 5.** Probabilistic analysis for a 1500 features model.

only the 28% of the software product line components, we can ensure that at least, the 75% of the generated products, are tested.

## 6 Conclusions

We have presented a probabilistic extension of our formal framework to specify and analyze SPLs. The main goal of this proposal is to alleviate the combinatorial explosion issue, where a vast number of combinations are generated by some of the algebra operators, of being unpractical to process the entire SPL. By including probabilistic information in our process algebra, we are able to generate relevant information for determining the probability of a given feature to be present in a valid product. We have provided two semantic frameworks for our language and have proved that they identify the same processes. In order to show the applicability of our approach, a tool containing the implementation of the denotational semantics for our probabilistic extension has been developed. This tool has been used to conduct an experimental study. The results of this study show that, using our approach, it is possible to compute the probability of each feature in the SPL to be present in a valid product. Thus, the testing process can focus on those features having a high probability of being included in a product.

We have two main lines for future work. First, it is important to develop mechanisms allowing us to simplify and/or optimize terms based on the results of the probabilistic analysis. In addition, we plan to find practical use cases to show the usefulness of having a probabilistic extension for SPLs.




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**Fig. 6.** Probabilistic analysis for a 1500 features model, decreasingly sorted.

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## A Results for the proof of Proposition 3

**Lemma 3.** Let  $P \in \text{SPLA}^{\mathcal{P}}$  and  $\mathbf{A} \in \mathcal{F}$ , then  $(pr, p) \in \text{prod}^{\mathcal{P}}(\mathbf{A}; P)$  if and only if

$$p = \sum \wr r \mid (pr', r) \in \text{prod}^{\mathcal{P}}(P) \wedge pr' \cup \{\mathbf{A}\} = pr \wr$$

*Proof.* The other transition of  $\mathbf{A}; P$  is  $\mathbf{A}; P \xrightarrow{\mathbf{A}}_1 Q$ . Then  $\mathbf{A}; P \xrightarrow{s}_p P$  if and only if

$$\mathbf{A}; P \xrightarrow{\mathbf{A}}_1 P \xrightarrow{s}_p Q \quad \wedge \quad s = \mathbf{A} \cdot s'$$

then

$$\begin{aligned} p &= \sum \wr r \mid \mathbf{A}; P \xrightarrow{s\checkmark}_p \text{nil} \wedge [s] = pr \wr = \\ &\sum \wr r \mid \mathbf{A}; P \xrightarrow{\mathbf{A}}_1 P \xrightarrow{s'\checkmark}_r \text{nil} \wedge [\mathbf{A} \cdot s'] = pr \wr \\ &\quad \sum \wr r \mid P \xrightarrow{s'\checkmark}_r \text{nil} \wedge \{\mathbf{A}\} \cup [s'] = pr \wr \\ &\sum \wr r \mid (pr', r) \in \text{prod}^{\mathcal{P}}(P) \wedge \{\mathbf{A}\} \cup pr' = pr \wr \end{aligned}$$

□

**Lemma 4.** Let  $P \in \text{SPLA}^{\mathcal{P}}$ ,  $\mathbf{A} \in \mathcal{F}$  and  $q \in (0, 1)$ , then  $(pr, p) \in \text{prod}^{\mathcal{P}}(\bar{\mathbf{A}};_q P)$  if and only if  $(pr, p) = (\emptyset, 1 - q)$  or

$$p = q \cdot \sum \wr r \mid (pr', r) \in \text{prod}^{\mathcal{P}}(P) \wedge pr' \cup \{\mathbf{A}\} = pr \wr$$

*Proof.* There exist two transitions to  $\bar{\mathbf{A}};_q P$ :  $\bar{\mathbf{A}};_q P \xrightarrow{\mathbf{A}}_q P$  and  $\bar{\mathbf{A}};_q P \xrightarrow{\checkmark}_{1-q} \text{nil}$ . So forth if  $\bar{\mathbf{A}};_q P \xrightarrow{s}_r Q$  then

- $s = \checkmark$  and  $r = 1 - q$ , or
- $s = \mathbf{A} \cdot s'$ ,  $P \xrightarrow{s}_{r'} Q$ , and  $r = q \cdot r'$ .

So, if  $pr = [\mathbf{A} \cdot s']$  then  $pr \neq \emptyset$ . So then  $(\emptyset, 1 - q) \in \text{prod}^{\mathcal{P}}(\bar{\mathbf{A}};_q P)$ . Now suppose  $pr \neq \emptyset$ , then  $(pr, p) \in \text{prod}^{\mathcal{P}}(\bar{\mathbf{A}};_q P)$  if and only if

$$\begin{aligned} d &= \sum \wr r \mid \bar{\mathbf{A}};_q P \xrightarrow{s\checkmark} \text{nil} \wedge [s] = pr \wr = \\ &\sum \wr r \mid \bar{\mathbf{A}};_q P \xrightarrow{\mathbf{A}}_q P \xrightarrow{s'\checkmark}_{r'} \text{nil} \wedge [\mathbf{A} \cdot s'] = pr \wedge r = q \cdot r' \wr = \\ &\quad \sum \wr r \mid P \xrightarrow{s'\checkmark}_{r'} \text{nil} \wedge \{\mathbf{A}\} \cup [s'] = pr \wedge r = q \cdot r' \wr = \\ &\sum \wr r \mid (pr', r') \in \text{prod}^{\mathcal{P}}(P) \wedge \{\mathbf{A}\} \cup pr' = pr \wedge r = q \cdot r' \wr = \\ &\quad q \cdot \sum \wr r' \mid (pr', r') \in \text{prod}^{\mathcal{P}}(P) \wedge \{\mathbf{A}\} \cup pr' = pr \wr \end{aligned}$$

□

**Lemma 5.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$  and  $q \in (0, 1)$ , then  $P \vee_q Q \xrightarrow{s}_r R$  if and only if



- $P \xrightarrow{s}_{r'} R \text{ y } r = q \cdot r', \circ$
- $Q \xrightarrow{s}_{r'} R \text{ y } r = (1 - q) \cdot r'$

*Proof.* This lemma is a consequence of rules [cho1] y [cho2] from the operational semantics. □

**Lemma 6.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$  and  $q \in (0, 1)$ , then  $(pr, p) \in \text{prod}^{\mathcal{P}}(P \vee_q Q)$  if and only if

$$p = \left( q \cdot \sum \{r \mid (pr, r) \in \text{prod}^{\mathcal{P}}(P)\} \right) + \left( (1 - q) \cdot \sum \{r \mid (pr, r) \in \text{prod}^{\mathcal{P}}(Q)\} \right)$$

*Proof.*  $(pr, p) \in \text{prod}^{\mathcal{P}}(P \vee_q Q)$  if and only if

$$\begin{aligned} p &= \sum \{r \mid P \vee_q Q \xrightarrow{s\checkmark}_r \text{nil}\} = \\ &= \sum \{r \mid (P \xrightarrow{s\checkmark}_{r'} \text{nil} \wedge r = q \cdot r') \vee (Q \xrightarrow{s\checkmark}_{r'} \text{nil} \wedge r = (1 - q) \cdot r')\} = \\ &= \sum \{r \mid P \xrightarrow{s\checkmark}_{r'} \text{nil} \wedge r = q \cdot r'\} + \sum \{r \mid Q \xrightarrow{s\checkmark}_{r'} \text{nil} \wedge r = (1 - q) \cdot r'\} = \\ &= q \cdot \sum \{r \mid P \xrightarrow{s\checkmark}_r \text{nil}\} + (1 - q) \cdot \sum \{r \mid Q \xrightarrow{s\checkmark}_r \text{nil}\} = \\ &= q \cdot \sum \{r \mid (pr, r) \in \text{prod}^{\mathcal{P}}(P)\} + (1 - q) \cdot \sum \{r \mid (pr, r) \in \text{prod}^{\mathcal{P}}(Q)\} \end{aligned}$$

□

**Definition 9.** Let  $s, s' \in \mathcal{F}^*$  be traces, we denote the set of traces obtained from alternate  $s$  and  $s'$  por  $\text{int}(s, s')$ . □

**Lemma 7.** Let  $P, Q \in \text{SPLA}^{\mathcal{P}}$ ,  $p, q \in (0, 1)$  and  $s, s' \in \mathcal{F}^*$  such  $p = \sum \{p' \mid P \xrightarrow{s\checkmark}_{p'} \text{nil}\}$  and  $q = \sum \{q' \mid Q \xrightarrow{s'\checkmark}_{q'} \text{nil}\}$  then

$$p \cdot q = \sum \{r \mid P \wedge Q \xrightarrow{s''\checkmark}_r \text{nil} \wedge s'' \in \text{int}(s, s')\}$$

*Proof.* By induction of  $|s| + |s'|$ .

$|s| + |s'| = 0$  Since  $P \wedge Q \xrightarrow{\checkmark}_r \text{nil}$  if and only if  $P \xrightarrow{\checkmark}_{r_1} \text{nil}$ ,  $Q \xrightarrow{\checkmark}_{r_2} \text{nil}$ , y  $r = r_1 \cdot r_2$ , behold the following:

$$\begin{aligned} & \sum \{r \mid P \wedge Q \xrightarrow{\checkmark}_r \text{nil}\} = \\ &= \sum \{r \mid P \xrightarrow{\checkmark}_{r_1} \text{nil} \wedge Q \xrightarrow{\checkmark}_{r_2} \text{nil} \wedge r = r_1 \cdot r_2\} = \\ &= \sum \{r_1 \cdot r_2 \mid P \xrightarrow{\checkmark}_{r_1} \text{nil} \wedge Q \xrightarrow{\checkmark}_{r_2} \text{nil}\} = \quad (1) \\ &= \sum \left\{ r_1 \cdot \left( \sum \{r_2 \mid Q \xrightarrow{\checkmark}_{r_2} \text{nil}\} \right) \mid P \xrightarrow{\checkmark}_{r_1} \text{nil} \right\} = \\ &= \sum \{r_1 \cdot q \mid P \xrightarrow{\checkmark}_{r_1} \text{nil}\} = q \cdot \sum \{r_1 \mid P \xrightarrow{\checkmark}_{r_1} \text{nil}\} = q \cdot p \end{aligned}$$

$|s| + |s'| > 0$  Suppose that  $|s| > 0$  (in the case  $|s'| > 0$  is symmetric). Let's consider that  $s = \mathbf{A} \cdot s_1$ . Now consider the multiset  $\mathcal{P} = \{P' \mid P \xrightarrow{\mathbf{A}}_{r'} P' \xrightarrow{s_1 \checkmark}_{p'} \text{nil}\}$  and given  $r_1 = \sum \{r \mid P \xrightarrow{\mathbf{A}}_r P' \wedge P' \in \mathcal{P}\}$  and  $p_1 = \sum \{r \mid P' \xrightarrow{s_1 \checkmark}_r \text{nil} \wedge P' \in \mathcal{P}\}$ . It easy to verify that  $p = r_1 \cdot p_1$ :

$$\begin{aligned}
p &= \sum \{r \mid P \xrightarrow{s \checkmark}_r \text{nil}\} = \\
&= \sum \{r' \cdot p' \mid P \xrightarrow{\mathbf{A}}_{r'} P' \xrightarrow{s_1 \checkmark}_{p'} \text{nil}\} = \\
\sum \int & r' \cdot \underbrace{\left( \sum \{p' \mid P' \xrightarrow{s_1 \checkmark}_{p'} \text{nil}\} \right)}_{p_1} \Big| P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P} \int = \quad (2) \\
&= p_1 \cdot \sum \{r' \mid P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P}\} = r_1 \cdot p_1
\end{aligned}$$

For any  $P' \in \mathcal{P}$ , and then for the inductive hypothesis we obtain

$$p' \cdot q = \sum \{r \mid P' \wedge Q \xrightarrow{s'' \checkmark}_r \wedge s'' \in \text{int}(s_1, s')\}$$

So forth

$$\begin{aligned}
&\sum \{r \mid P' \in \mathcal{P} \wedge P' \wedge Q \xrightarrow{s'' \checkmark}_r \wedge s'' \in \text{int}(s_1, s')\} = \\
&\sum \{p' \cdot q \mid P' \in \mathcal{P} \wedge P' \xrightarrow{s_1 \checkmark}_{p'} \text{nil} \wedge s'' \in \text{int}(s_1, s')\} \quad (3) \\
&= q \cdot \sum \{r \mid P' \xrightarrow{s_1 \checkmark}_{\text{nil}} \wedge P' \in \mathcal{P}\} = p_1 \cdot q
\end{aligned}$$

then for any  $P' \in \mathcal{P}$  we obtain  $P \wedge Q \xrightarrow{s'' \checkmark}_r \text{nil}$  where  $P \xrightarrow{\mathbf{A}}_{r'} P'$ ,  $r = \frac{r'}{2} \cdot p' \cdot q$  y  $s''$  is the alternation of  $s$  and  $s'$ . So forth

$$\begin{aligned}
&\sum \{r \mid P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{r_1}{2}} P' \wedge Q \xrightarrow{s'' \checkmark}_{r_2} \text{nil} \wedge P' \xrightarrow{\mathbf{A}}_{r_1} P' \wedge \\
&\quad r = \frac{r_1}{2} \cdot r_1 \wedge s'' \in \text{int}(s_1, s')\} = \\
\sum \int & \frac{r'}{2} \cdot r'' \Big| P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \wedge Q \xrightarrow{s'' \checkmark}_{r''} \text{nil} \wedge s'' \in \text{int}(s_1, s') \int = \\
&\sum \int \frac{r'}{2} \cdot \underbrace{\left( \sum \int \frac{r''}{r''} \Big| P' \wedge Q \xrightarrow{s'' \checkmark}_{r''} \text{nil} \wedge s'' \in \text{int}(s_1, s') \int \right)}_{\text{induction hypothesis: } p_1 \cdot q} \Big| P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P} \int = \quad (4) \\
&= \sum \int \frac{r'}{2} \cdot (p_1 \cdot q) \Big| P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P} \int = \\
&= \frac{(p_1 \cdot q)}{2} \cdot \sum \{r' \mid P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P}\} = \\
&= \frac{1}{2} (p_1 \cdot q \cdot r_1) = \frac{1}{2} (p \cdot q)
\end{aligned}$$

Equation 4 groups all probabilities of alternating  $s$  and  $s'$  where the first action of  $s$  is given in first place. Then we have to group the probabilistic information when the first action of  $s'$  happens in first place.

There are two possibilities, if these actions exist or not. Depending on  $s'$  we can obtain the following options.

$|s'| = 0$  In this case we have  $q = \sum \{q' \mid Q \xrightarrow{\checkmark}_{q'} \mathbf{nil}\}$ , If  $Q \xrightarrow{\checkmark}_{q'} \mathbf{nil}$ , when applying the rule [con4] and then obtain  $P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{r' \cdot q'}{2}} P_1$ . In this case we obtain

$$\begin{aligned}
& \sum \{r \mid P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{q' \cdot r'}{2}} P' \xrightarrow{s_1 \checkmark}_{p'} \mathbf{nil} \wedge r = p' \cdot \frac{q' \cdot r'}{2}\} = \\
& \quad \sum \{\frac{1}{2} \cdot (p' \cdot r' \cdot q' \mid P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{q' \cdot r'}{2}} P' \xrightarrow{s_1 \checkmark}_{p'} \mathbf{nil})\} = \\
& \sum \{\frac{1}{2} \cdot (p' \cdot r' \cdot \underbrace{(\sum \{q' \mid Q \xrightarrow{\checkmark}_{q'} \mathbf{nil}\})}_q \mid P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \xrightarrow{s_1 \checkmark}_{p'} \mathbf{nil})\} = \\
& \quad \frac{q}{2} \cdot \sum \{r' \cdot \underbrace{(\sum \{p' \mid P' \xrightarrow{s_1 \checkmark}_{p'} \mathbf{nil})\}}_{p_1} \mid P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P}\} = \\
& \quad \frac{1}{2} (q \cdot p_1) \cdot \underbrace{(\sum \{r' \mid P \xrightarrow{\mathbf{A}}_{r'} P' \wedge P' \in \mathcal{P}\})}_{r_1} = \frac{1}{2} \cdot (q \cdot p_1 \cdot r_1) = \frac{1}{2} (q \cdot p)
\end{aligned} \tag{5}$$

The only transition of  $P \wedge Q$  that allows to alternate  $s$  and  $s'$  have the form

1.  $P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{r'}{2}} P' \wedge Q \xrightarrow{s'' \checkmark}_{p'} \mathbf{nil}$  as is indicated above , or
2.  $P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{q' \cdot r'}{2}} P' \xrightarrow{s'' \checkmark}_{p'} \mathbf{nil}$ .

So forth

$$\begin{aligned}
& \sum \{r \mid P \wedge Q \xrightarrow{s \checkmark} \mathbf{nil}\} = \\
& \sum \{r \mid P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{r_1}{2}} P' \wedge Q \xrightarrow{s'' \checkmark}_{r_2} \mathbf{nil} \wedge P' \xrightarrow{\mathbf{A}}_{r_1} P' \wedge \\
& \quad r = \frac{r_1}{2} \cdot r_1 \wedge s'' \in \text{int}(s_1, s')\} + \\
& \sum \{r \mid P \wedge Q \xrightarrow{\mathbf{A}}_{\frac{q' \cdot r'}{2}} P' \xrightarrow{s_1 \checkmark}_{p'} \mathbf{nil} \wedge r = p' \cdot \frac{q' \cdot r'}{2}\} = \\
& \quad \frac{1}{2} (p \cdot q) + \frac{1}{2} (p \cdot q) = p \cdot q
\end{aligned} \tag{6}$$

$|s'| > 0$  Let consider  $s' = \mathbf{B} \cdot s_2$ . In this case we consider the alternations where  $Q$  produces the feature  $\mathbf{B}$  in first place, which is, that first we apply the rule [con2]. Considering the multiset  $\mathcal{Q} = \{Q' \mid Q \xrightarrow{\mathbf{B}}_{r} Q' \xrightarrow{s_2 \checkmark}_{q'} \mathbf{nil}\}$ , and given  $r_2 = \sum \{r \mid Q \xrightarrow{\mathbf{B}}_{r} Q' \wedge Q' \in \mathcal{Q}\}$  and  $q_1 = \sum \{r \mid Q' \xrightarrow{s_2 \checkmark}_{r} \mathbf{nil} \wedge Q' \in \mathcal{Q}\}$ . With a similar reasoning to te equations (1) and (2) we obtain that  $q = r_2 \cdot q_1$  and

$$\begin{aligned}
& \sum \{r \mid P \wedge Q \xrightarrow{\mathbf{B}}_{\frac{r_1}{2}} P \wedge Q' \xrightarrow{s'' \checkmark}_{r_2} \mathbf{nil} \wedge \\
& \quad r = \frac{r_1}{2} \cdot r_1 \wedge s'' \in \text{int}(s, s_2)\} = \frac{1}{2} (p \cdot q)
\end{aligned} \tag{7}$$

The only transition of  $P \wedge Q$  that implies to alternate  $s$  and  $s'$  have the form:

1.  $P \wedge Q \xrightarrow{A}_{p' \cdot \frac{r}{2}} P' \wedge Q \xrightarrow{s'' \checkmark}_{p'} \mathbf{nil}$  where  $s''$  is an alternation of  $s_1$  and  $s'$ , or
2.  $P \wedge Q \xrightarrow{B}_{q' \cdot \frac{r}{2}} P \wedge Q' \xrightarrow{s'' \checkmark}_{p'} \mathbf{nil}$  where  $s''$  is an alternation of  $s$  and  $s_2$ ,

So forth,

$$\begin{aligned}
& \sum \{r \mid P \wedge Q \xrightarrow{s \checkmark} \mathbf{nil}\} = \\
& \sum \{r \mid P \wedge Q \xrightarrow{A}_{\frac{r_1}{2}} P' \wedge Q \xrightarrow{s'' \checkmark}_{r_2} \mathbf{nil} \wedge P' \xrightarrow{A}_{r_1} P' \wedge \\
& \quad r = \frac{r_1}{2} \cdot r_1 \wedge s'' \in \text{int}(s_1, s')\} + \\
& \sum \{r \mid P \wedge Q \xrightarrow{B}_{\frac{r_1}{2}} P \wedge Q' \xrightarrow{s'' \checkmark}_{r_2} \mathbf{nil} \wedge Q' \xrightarrow{B}_{r_1} Q' \wedge \\
& \quad r = \frac{r_1}{2} \cdot r_1 \wedge s'' \in \text{int}(s, s_2)\} = \\
& \quad \frac{1}{2}(p \cdot q) + \frac{1}{2}(p \cdot q) = p \cdot q
\end{aligned} \tag{8}$$

□

**Lemma 8.** Let  $P \in \text{SPLA}^{\mathcal{P}}$ ,  $A \in \mathcal{F}$  and  $P \xrightarrow{s \checkmark}_p \mathbf{nil}$ .

1.  $A \in s$  if and only if  $P \Rightarrow A \xrightarrow{s \checkmark}_p \mathbf{nil}$ .
2.  $A \notin s$  if and only if  $P \Rightarrow A \xrightarrow{sA \checkmark}_p \mathbf{nil}$ .

*Proof.* In both cases the demonstration is made by induction of the length of  $|s|$ .

□

**Lemma 9.** Let  $P \in \text{SPLA}^{\mathcal{P}}$ ,  $A \in \mathcal{F}$ ,  $s \in \mathcal{F}^*$  and  $p \in (0, 1)$ .  $P \xrightarrow{s \checkmark}_p \mathbf{nil}$ , if and only if  $A \setminus P \xrightarrow{s \checkmark}_p \mathbf{nil}$  and  $A \notin s$ .

*Proof.* The demonstration is simple by the induction on the length of  $s$ .

□

**Lemma 10.** Let  $P \in \text{SPLA}^{\mathcal{P}}$ ,  $A, B \in \mathcal{F}$ ,  $s \in \mathcal{F}^*$  and  $p \in (0, 1)$ . Then  $P \xrightarrow{s \checkmark}_p \mathbf{nil}$  if and only if  $A \Rightarrow B$  in  $P \xrightarrow{s' \checkmark}_p \mathbf{nil}$  and  $s'$  and it has some of the forms:  $A \notin s$  and  $s' = s$ ,  $B \in s$  and  $s' = s$ , or  $A \in s$ ,  $B \notin s$  and  $s' = s \cdot B$ .

*Proof.* By induction of the length of  $s$ .

$|s| = 0$  In this case  $P \xrightarrow{\checkmark}_p \mathbf{nil}$ . We obtain the result applying the rule [req3].  
 $|s| > 0$  Now we can distinguish three cases depending on the first feature of  $s$ :

$s = As_1$ . In this case exists  $p_1, q \in (0, 1)$  such as  $P \xrightarrow{A}_{p_1} P_1 \xrightarrow{s_1\checkmark}_q \text{nil}$ .  
 When applying the rule [req2] we obtain  $A \Rightarrow B$  in  $P \xrightarrow{A}_{p_1} P_1 \Rightarrow B$ . We obtain the result when applying the lemma 8.

$s = Bs_1$ . In this case exists  $p_1, q \in (0, 1)$  such as  $P \xrightarrow{A}_{p_1} P_1 \xrightarrow{s_1\checkmark}_q \text{nil}$ .  
 When applying the rule [req2] we obtain  $A \Rightarrow B$  in  $P \xrightarrow{B}_{p_1} P_1 \Rightarrow A$ . We obtain the result when applying the lemma 8.

$s = Cs_1$  **with**  $C \neq A$  **y**  $C \neq B$ . In this case exists  $p_1, q \in (0, 1)$  such as  $P \xrightarrow{C}_{p_1} P_1 \xrightarrow{s_1\checkmark}_q \text{nil}$ . When applying the rule [req1], we obtain  $A \Rightarrow B$  in  $P \xrightarrow{C}_{p_1} P_1 \Rightarrow A$ , and then the result of applying the inductive hypothesis over  $s_1$ .

□

**Lemma 11.** Let  $P \in \text{SPLA}^{\mathcal{P}}$ ,  $A, B \in \mathcal{F}$ ,  $s \in \mathcal{F}^*$  and  $p \in (0, 1)$ . Then  $P \xrightarrow{s\checkmark}_p \text{nil}$  if and only if  $A \not\Rightarrow B$  in  $P \xrightarrow{s\checkmark}_p \text{nil}$ ,  $A \notin s$  and  $B \notin s$ .

*Proof.* By the induction of the length of  $s$ .

$|s| = 0$  In this case  $P \xrightarrow{\checkmark}_p \text{nil}$ . We obtain the result of applying the rule [excl4].  
 $|s| > 0$  Now it is possible to distinguish three cases depending on the first feature of  $s$ :

$s = As_1$ . In this case exists  $p_1, q \in (0, 1)$  such that  $P \xrightarrow{A}_{p_1} P_1 \xrightarrow{s_1\checkmark}_q \text{nil}$ .  
 When applying the rule [req2] we obtain  $A \Rightarrow B$  in  $P \xrightarrow{A}_{p_1} P_1 \setminus B$ . Now based on Lemma 8,

- $B \in s_1$  if and only if  $P_1 \Rightarrow B \xrightarrow{s_1\checkmark}_q \text{nil}$ .
- $B \notin s_1$  if and only if  $P_1 \Rightarrow B \xrightarrow{s_1B\checkmark}_q \text{nil}$ .

$s = Cs_1$  **with**  $C \neq A$ . In this case is  $p_1, q \in (0, 1)$  such that  $P \xrightarrow{C}_{p_1} P_1 \xrightarrow{s_1\checkmark}_q \text{nil}$ . When applying rule [req1], we obtain  $A \Rightarrow B$  in  $P \xrightarrow{C}_{p_1} P_1 \Rightarrow A$ , and then the result is obtained when applying the inductive hypothesis over  $s_1$ .

□

## B Proof of Proposition 4

**Proposition 6.**  $P[\mathcal{A}] \xrightarrow{s}_r Q[\mathcal{A}]$  if and only if  $r = \sum \lambda p \mid P \xrightarrow{s'}_p Q, s = s'[\mathcal{A}]$

*Proof.* The proof is achieved by induction over the length of the trace  $s$ . If the length is zero the result is trivial. Then it is supposed that  $s = A \cdot s_1$ . If  $A = \perp$  then any transition  $P[\mathcal{A}] \xrightarrow{s}_p Q[\mathcal{A}]$  can be divided in transitions, possibly more than one, for example.

$$P[\mathcal{A}] \xrightarrow{\perp}_{r_1} P_1[\mathcal{A}] \xrightarrow{s_1}_{r_2} Q$$

then we have

$$r = \sum \{\lambda p \mid P[\mathcal{A}] \xrightarrow{s}_p Q\} = \sum \{\lambda r_1 \cdot r_2 \mid P[\mathcal{A}] \xrightarrow{\perp}_{r_1} P_1[\mathcal{A}] \xrightarrow{s_1}_{r_2} Q\} = \\ \sum \{\lambda r'_1 \cdot r_2 \mid P[\mathcal{A}] \xrightarrow{\mathbf{B}}_{r'_1} P'_1[\mathcal{A}] \xrightarrow{s_1}_{r_2} Q, \mathbf{B} \in \mathcal{A}\}$$

Now for each one of  $r'_1$ , we can apply the inductive method to each one of the transitions  $P'_1[\mathcal{A}] \xrightarrow{s_1}_{r_2} Q$  to obtain  $r_2 = \sum \{\lambda r_2' \mid P_1 \xrightarrow{s'_1}_{r_2'} Q, s_1 = s'_1[\mathcal{A}]\}$ . Continuing the last equation:

$$\sum \{\lambda r'_1 \cdot r_2 \mid P[\mathcal{A}] \xrightarrow{\mathbf{B}}_{r'_1} P'_1[\mathcal{A}] \xrightarrow{s_1}_{r_2} Q, \mathbf{B} \in \mathcal{A}\} = \\ \sum \{\lambda r'_1 \cdot r_2' \mid P[\mathcal{A}] \xrightarrow{\mathbf{B}}_{r'_1} P'_1 \xrightarrow{s'_1}_{r_2'} Q, \mathbf{B} \in \mathcal{A}, s_1 = s'_1[\mathcal{A}]\} = \\ \sum \{\lambda r_1 \cdot r_2' \mid P[\mathcal{A}] \xrightarrow{\perp}_{r_1} P_1 \xrightarrow{s'_1}_{r_2'} Q, \mathbf{B} \in \mathcal{A}, s_1 = s'_1[\mathcal{A}]\} = \\ \sum \{\lambda r \mid P \xrightarrow{s'}_r Q, s = s'[\mathcal{A}]\}$$

The case when  $\mathbf{A} \notin \mathcal{A}$  is similar to the last one, we just the to skip the step from  $\mathbf{B}$  to  $\perp$ .

□

*Proof of Proposition 4*  $(pr, p) \in \mathbf{prod}^{\mathcal{P}}(P[\mathcal{A}])$  if and only if

$$p = \sum \{\lambda r \mid P[\mathcal{A}] \xrightarrow{s'}_r P'[\mathcal{A}], pr = [s]\} = \\ \sum \{\lambda r \mid P \xrightarrow{s'}_r P', s = s'[\mathcal{A}], pr = [s]\} = \\ \sum \{\lambda r \mid P \xrightarrow{s'}_r P', s = pr[\mathcal{A}]\} = \\ \sum \{\lambda r \mid (pr', r) \in \mathbf{prod}^{\mathcal{P}}(P), pr' = pr[\mathcal{A}]\} =$$

So,  $(pr, p) \in \mathbf{prod}^{\mathcal{P}}(P[\mathcal{A}])$  if and only if  $(pr, p) \in \llbracket (\mathbf{prod}^{\mathcal{P}}(P))[\mathcal{A}] \rrbracket^{\mathcal{P}}$